

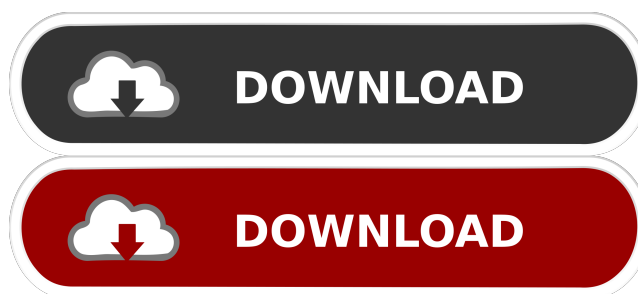
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Wade's book is very good. I have a couple of minor quibbles about it (mostly related to one section which I found a little complicated and a couple of sub-topics with a few references), but Wade's. But it also gives some coverage of QM that I felt was lacking elsewhere. It should help some students with the basic concepts. Bourne's book is excellent. Also gives a good discussion of the theory, leaving aside everything that can be deduced from the Maxwell's equations, and actually spends more time on the experimental side. This may be a drawback for some, but certainly helps students grasp what it is that makes the experiment work. Like Wade, it is not a QM book

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and relies on Bourne's other material, but is a good complement to it. In short, I'd recommend one of these two books to anyone who needs a primer on this material, but are already familiar with the basics. Chapter 1. Introduction and Review of the Classical Mechanics of Rigid Body Problems. For all practical purposes, a particle in a rigid body may be regarded as a particle in a centrally-symmetric . In this section, we review the kinematics and mechanics of a particle in a rigid body. We review Newton's equations of motion for the rigid body in . Since Newton's laws are equivalent to the Euler's equations of motion of the rigid body, the review of the rigid body kinematics is also a review of Newton's laws. Newton's laws of mechanics are presented in the following chapters. In this section, we review these laws in, where we define the force and the vector resultant and potential. Newton's laws of mechanics are given in Chapter 5. At the end of this section, we give the path integral formulation of the (rigid body) kinematics. The path integral formulation generalizes the perturbation theory that we used in previous chapters to the exact mechanics for rigid body problems. This section contains material very close to that in . But we state it here in a form more compatible with the form in the other chapters in the book. The goal of this section is to put a few basic facts about the rigid body problem at our disposal. Most of the basic facts about the rigid body mechanics are of Newtonian origin. Of course, the 2d92ce491b